

Team Project: Tharsus

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Outline

1. Presentation of the project

- a) Tharsus
- b) The Problem
- c) Data and tools

2. Methodology

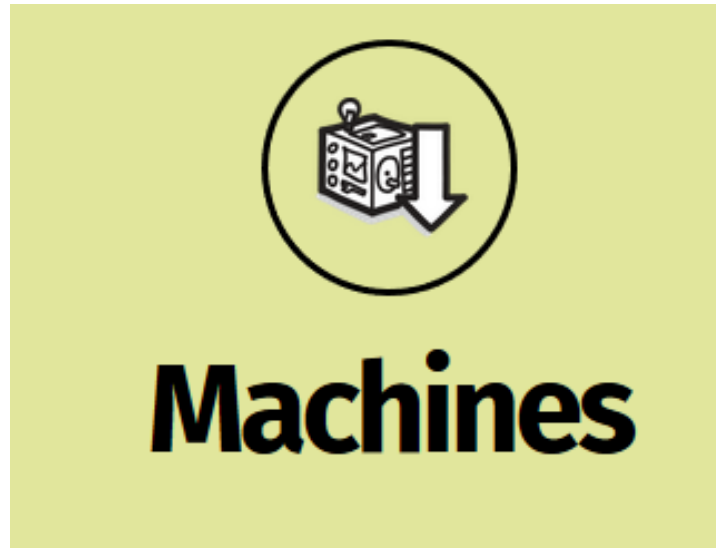
- a) Background subtraction
- b) Object detection algorithm (YOLO)
- c) Path tracking

3. Conclusions

The Project

THARSUS

is a robotics company



Designing and Manufacturing

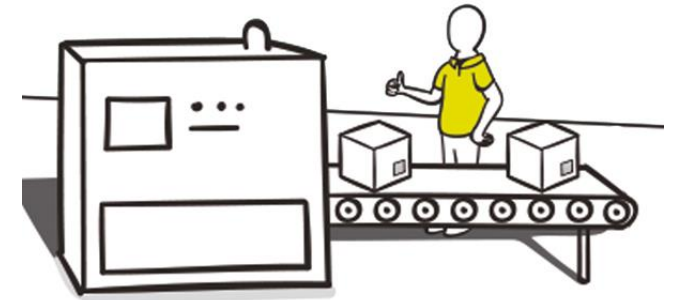


<https://www.tharsus.co.uk/>

THARSUS is a robotics company

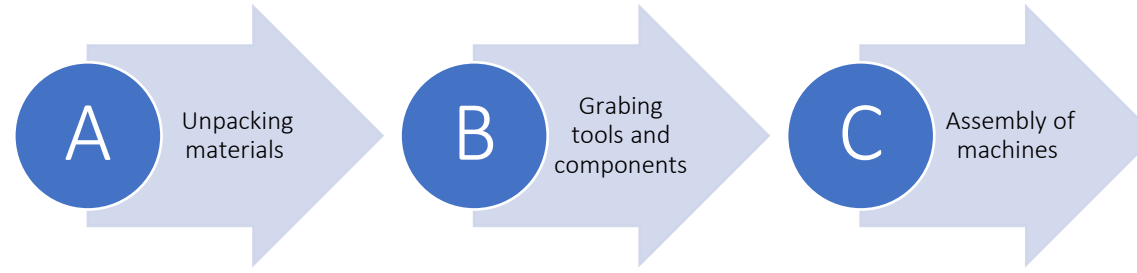


Looking for a
manufacturing partner?

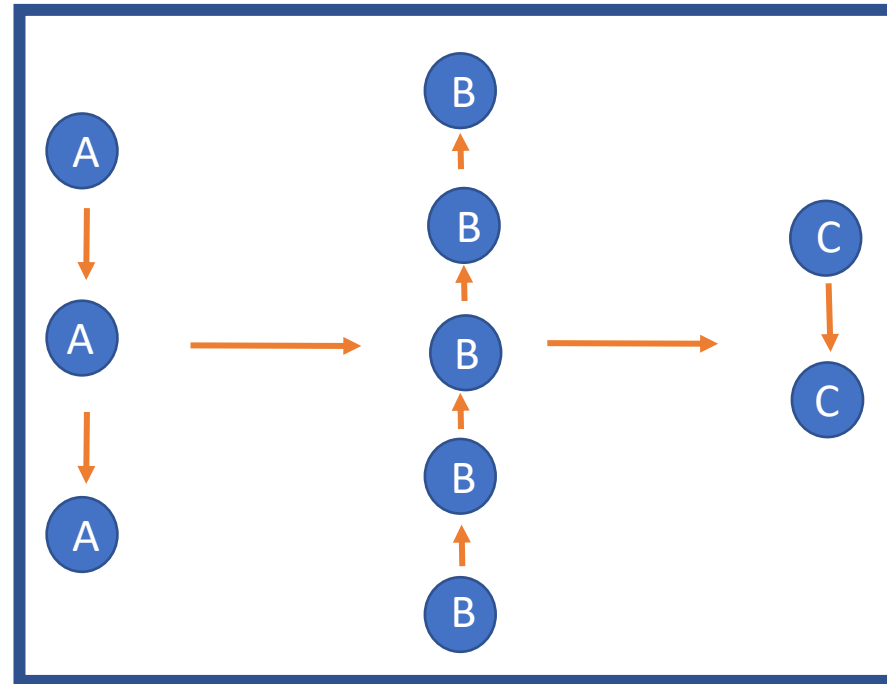


<https://www.tharsus.co.uk/>

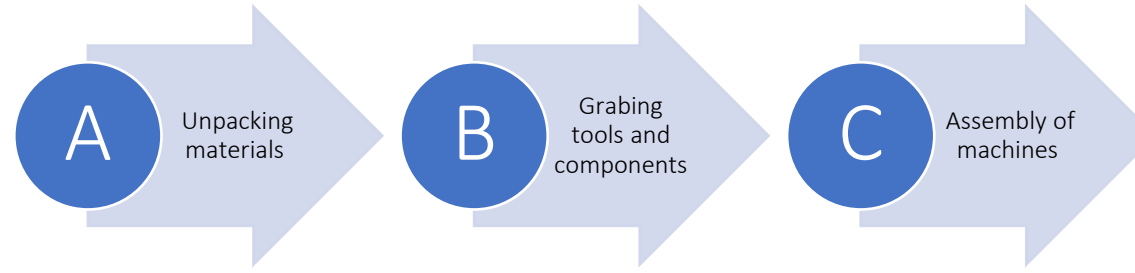
Production line: The life in the workshop



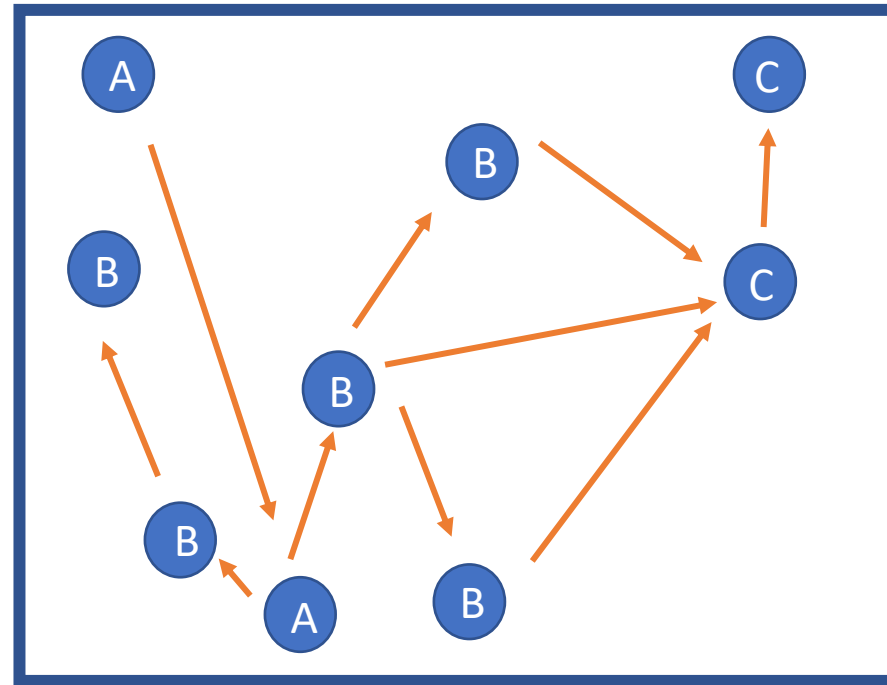
Ideal Case:



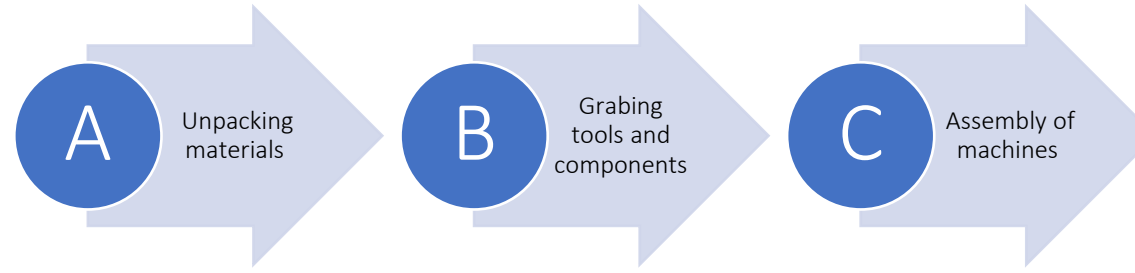
Production line: The life in the workshop



Real Case:

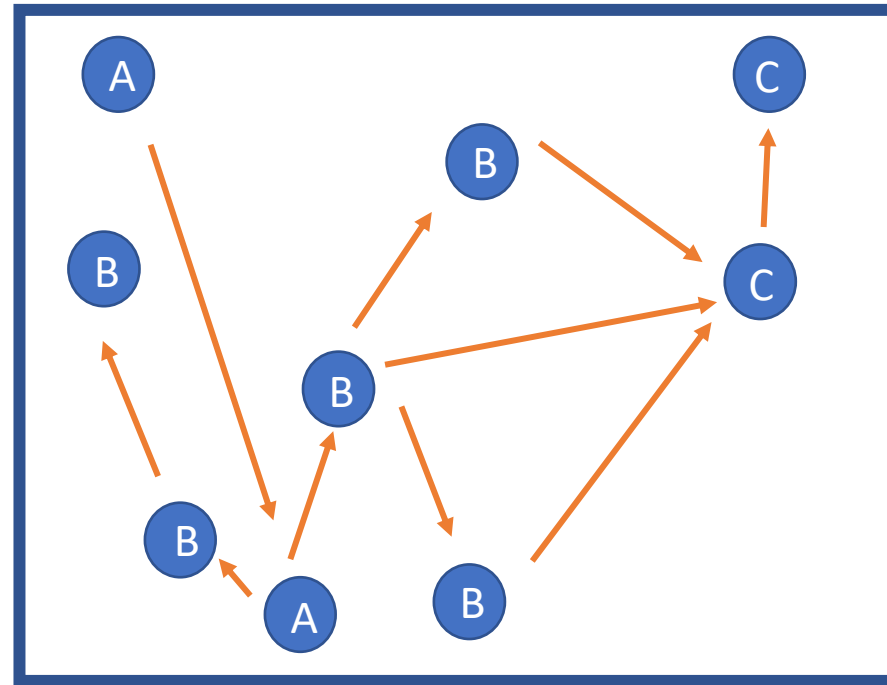


Production line: The life in the workshop



Real Case:

Is it possible to register how well distributed is the workshop?



How to approach to the problem?

Track the movement of people in a large area:

- Recording the **activities of a person in the production line**
- **Identify the person**
- Repeat during several minutes and for different people

Examine the data to find ineffectively located spots:

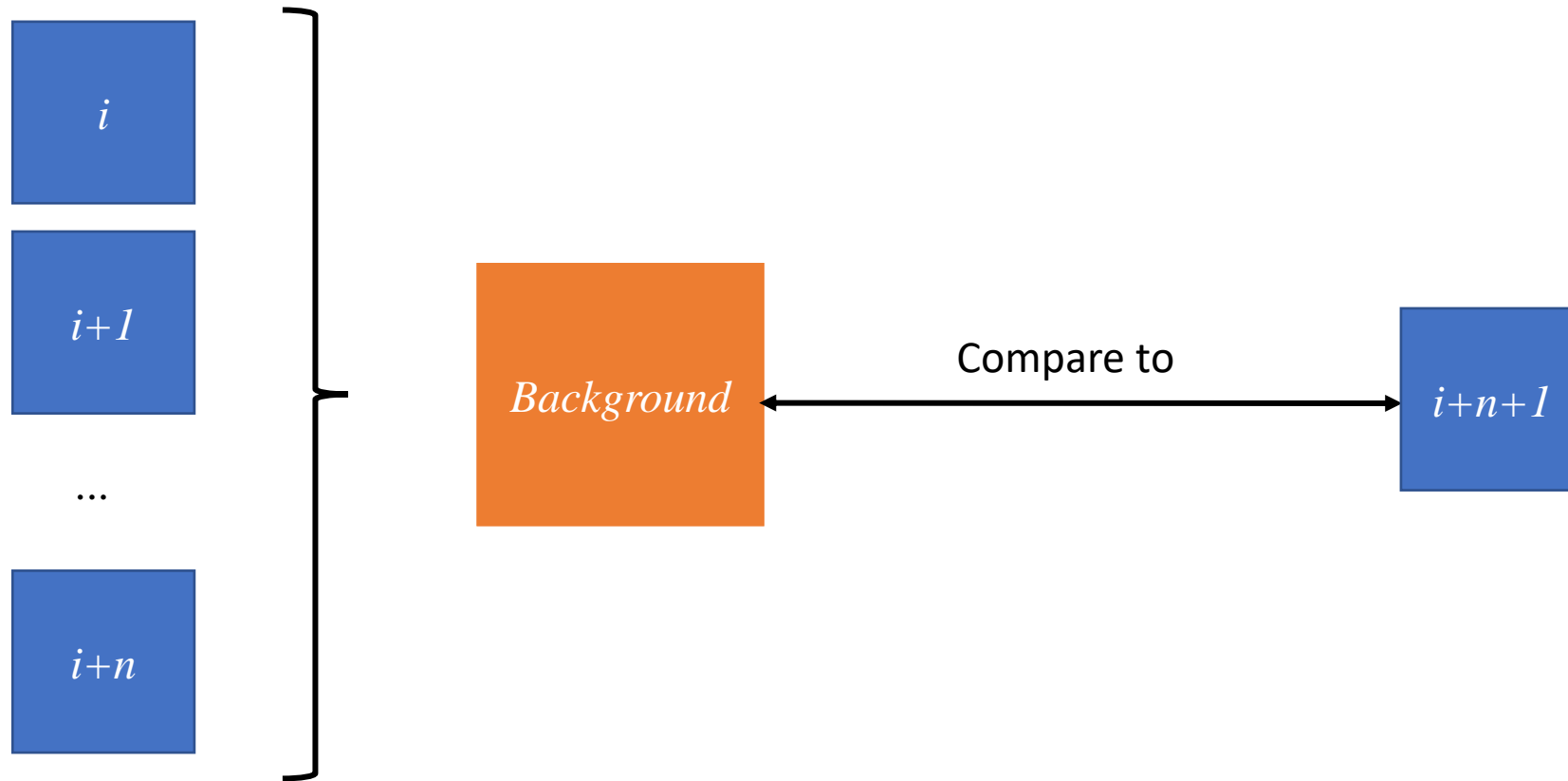
- A **RaspberryPi camera** is used to register the data
- **Python, OpenCV** and some object detection algorithms can be used to do the analysis



<https://opencv.org/>

Methodology

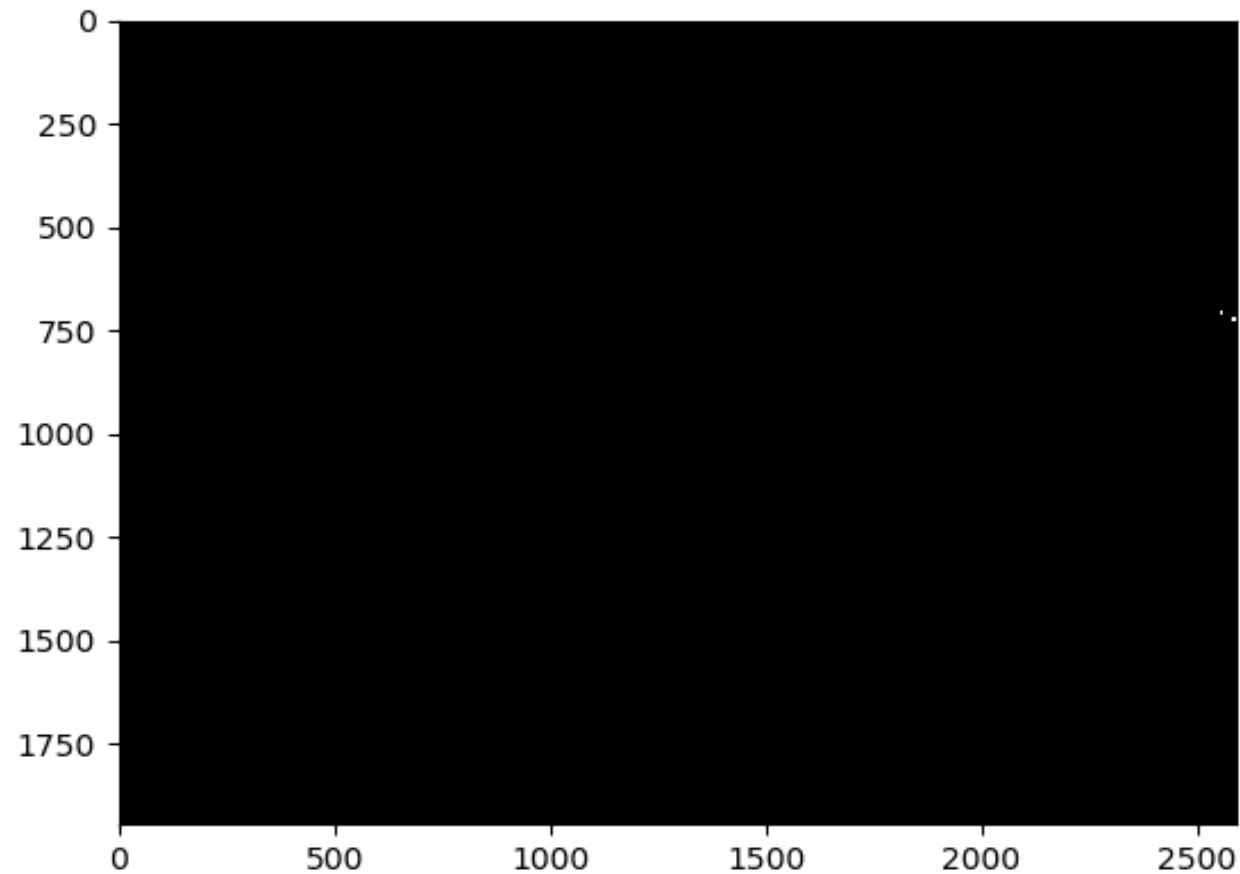
Use background subtraction in order to detect movement



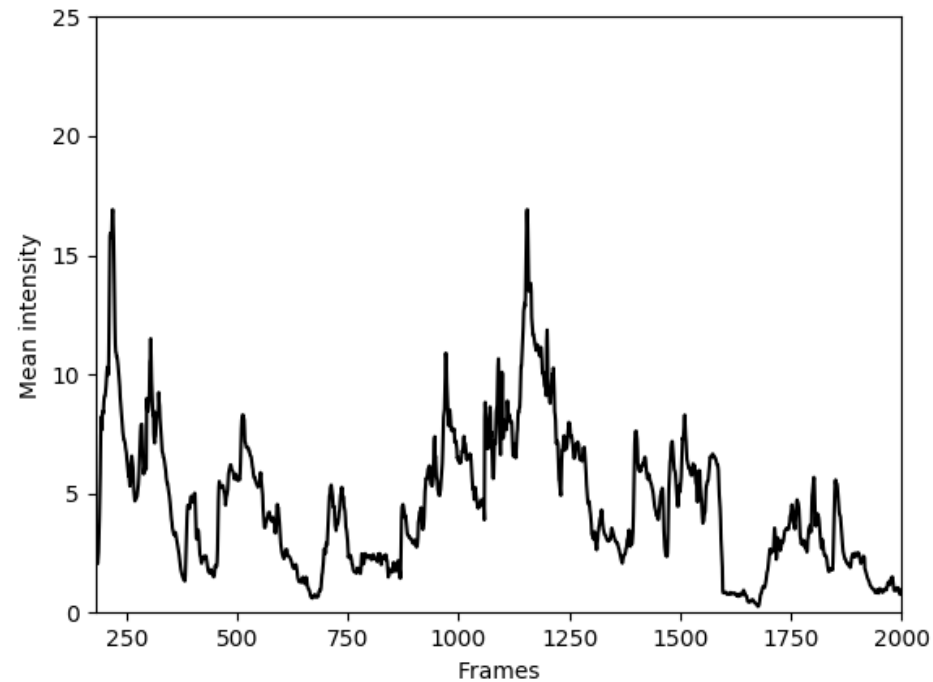
Use background subtraction in order to detect movement



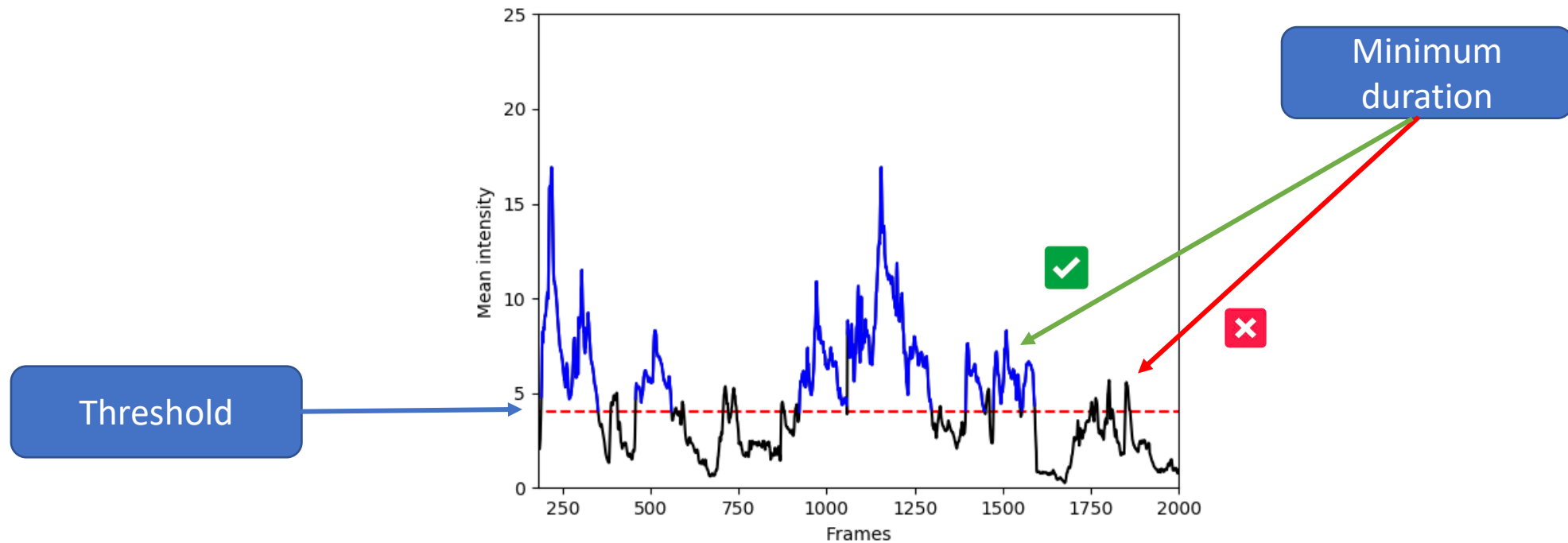
Use background subtraction in order to detect movement



Plot Intensity vs time to detect high activity segments



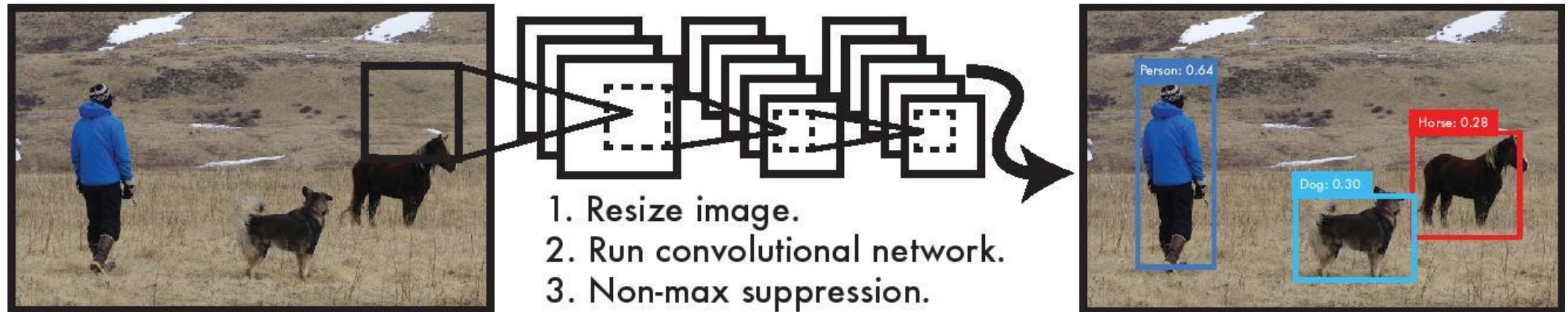
Plot Intensity vs time to detect high activity segments



YOLO (You Only Look Once):

Unified, Real-Time Object Detection

[arXiv:1506.02640](https://arxiv.org/abs/1506.02640)



Redmon et al. (2015)

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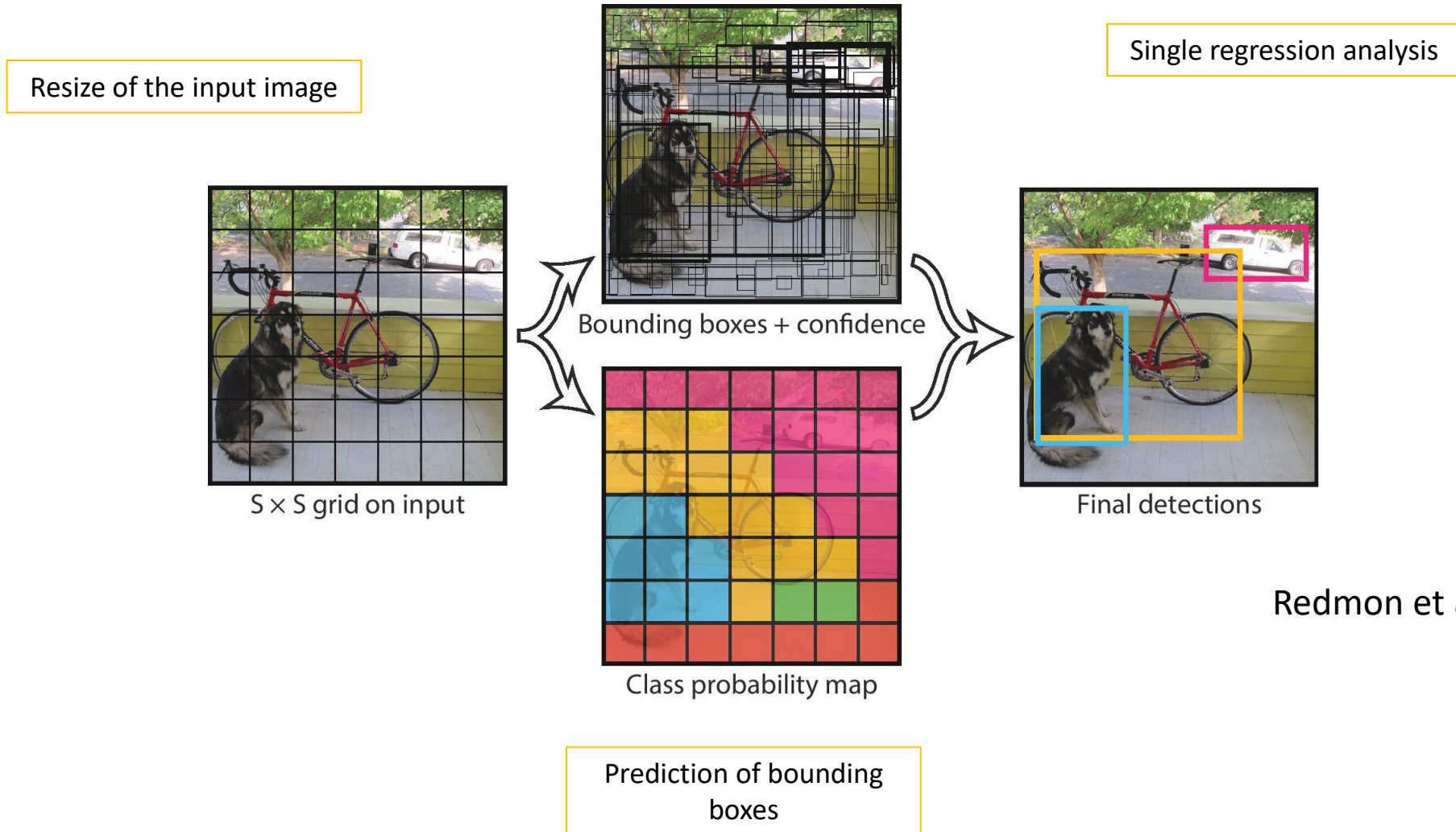


<https://pjreddie.com/darknet/yolo/>

YOLO (You Only Look Once):

Unified, Real-Time Object Detection

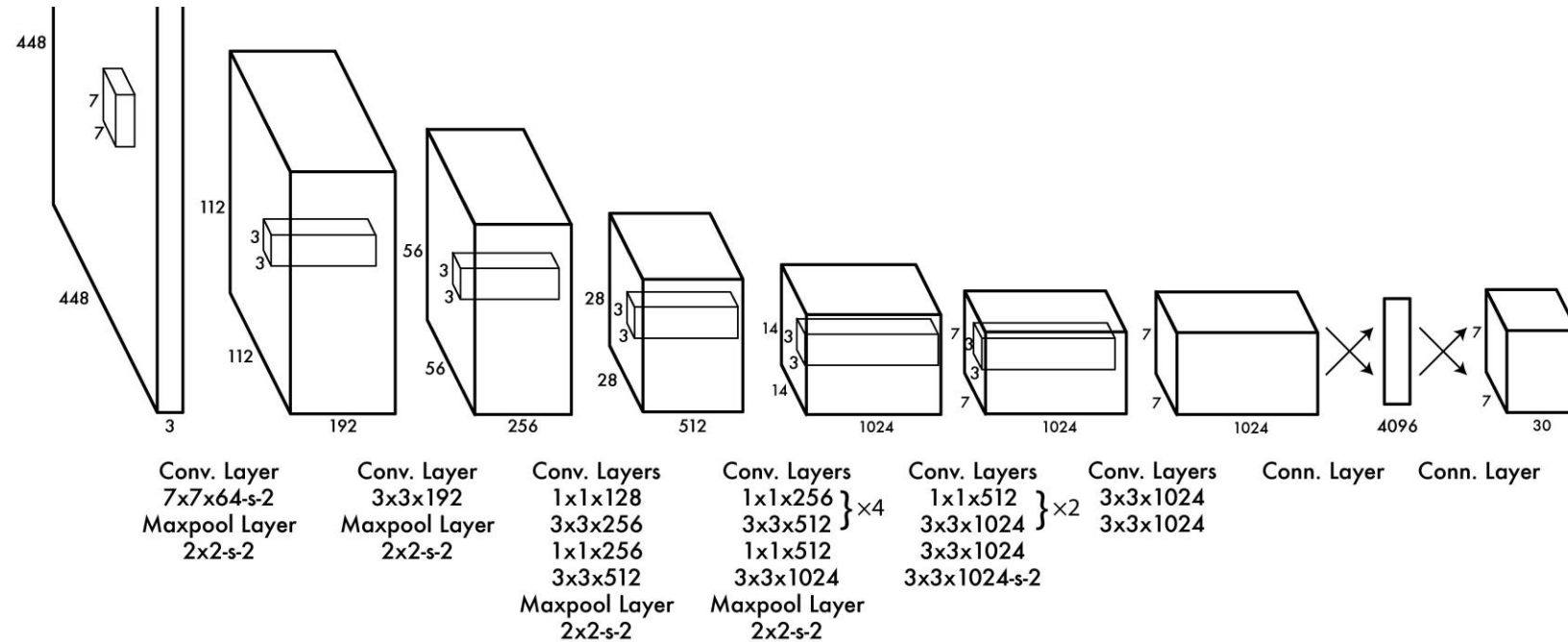
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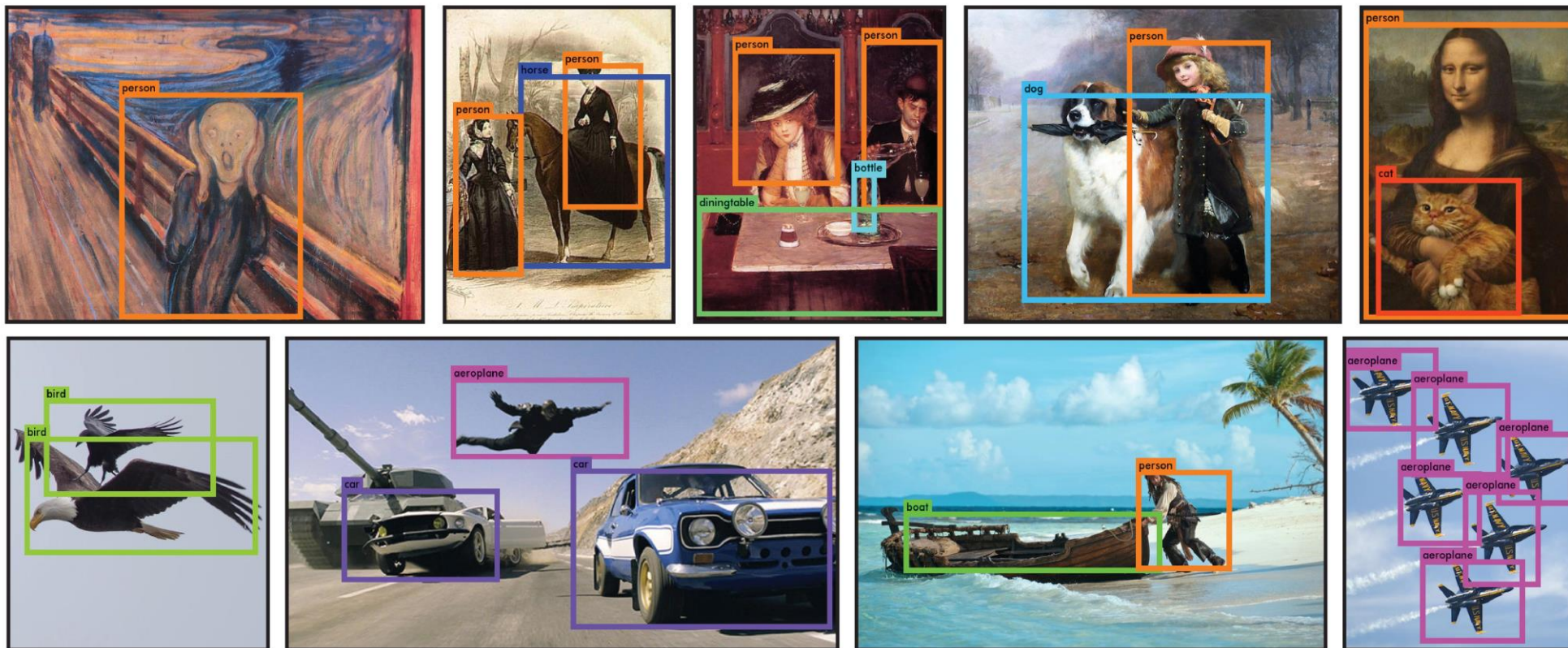


Redmon et al. (2015)

YOLO (You Only Look Once):

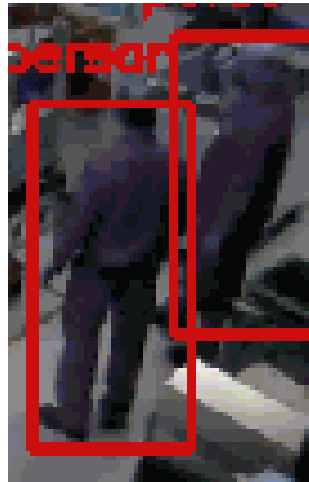
Unified, Real-Time Object Detection

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Can we apply YOLO to this problem?



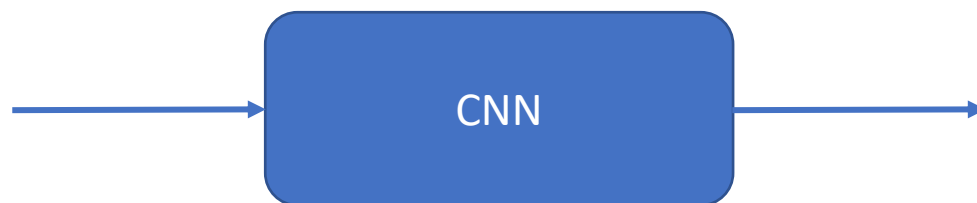
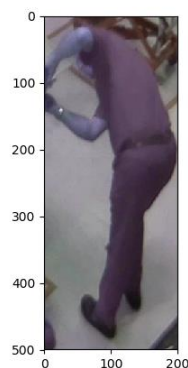
- Short answer: Yes. Nevertheless, limitations are present in the process (open problem).
- We apply YOLO to identify the individuals on every frame.
- Workers path at the workshop can be tracked on real time.

YOLO outputs

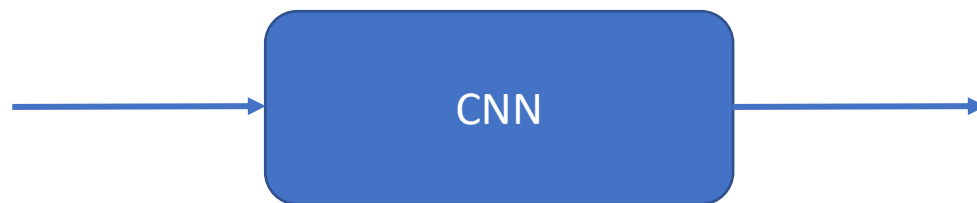
- Once a 'Person' is detected, useful information is saved.
- Pixel position (x,y), width and height of YOLO output boxes, and confidence of the YOLO class.
- Can we find all the tracks of one individual person?



Path tracking: the simplest approach?

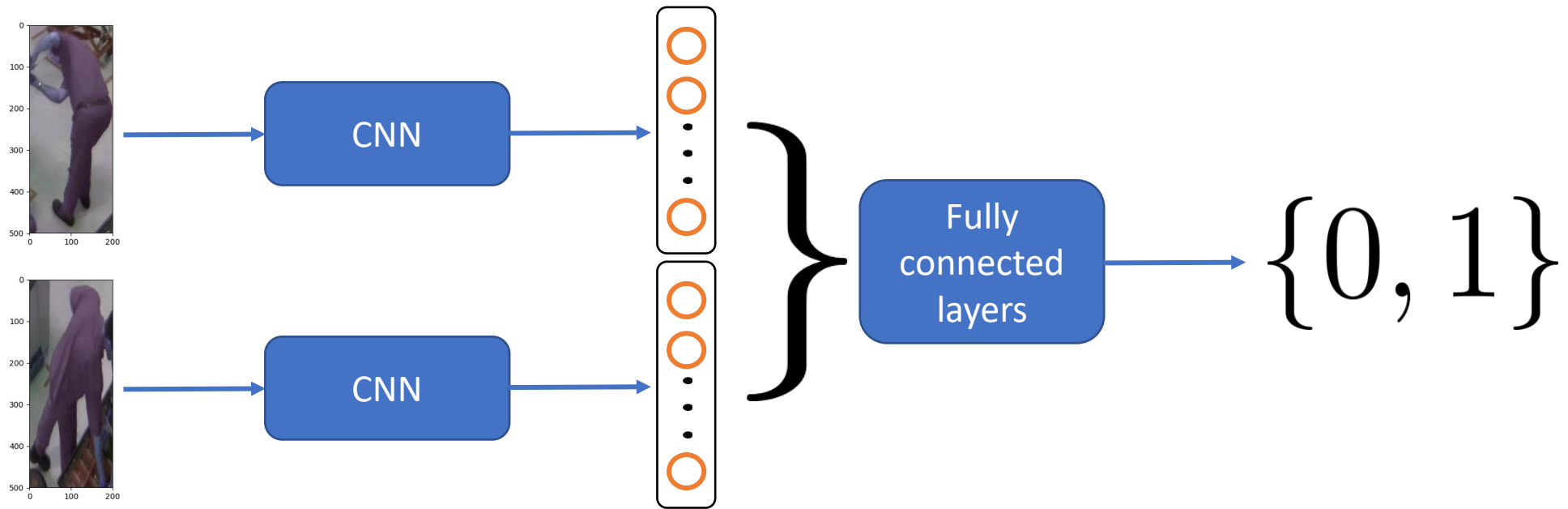


$\{1\}$

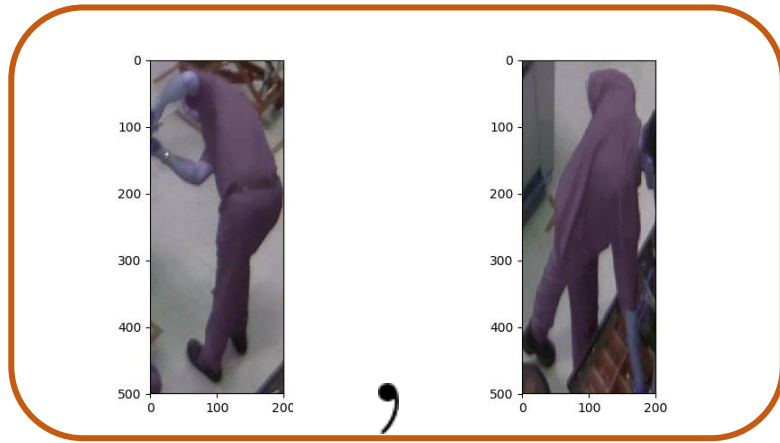


$\{2\}$

Path tracking: siamese network approach

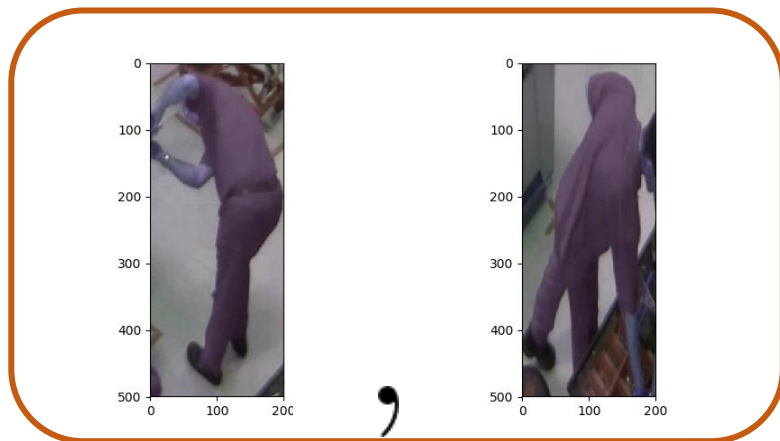


Path tracking: siamese network approach

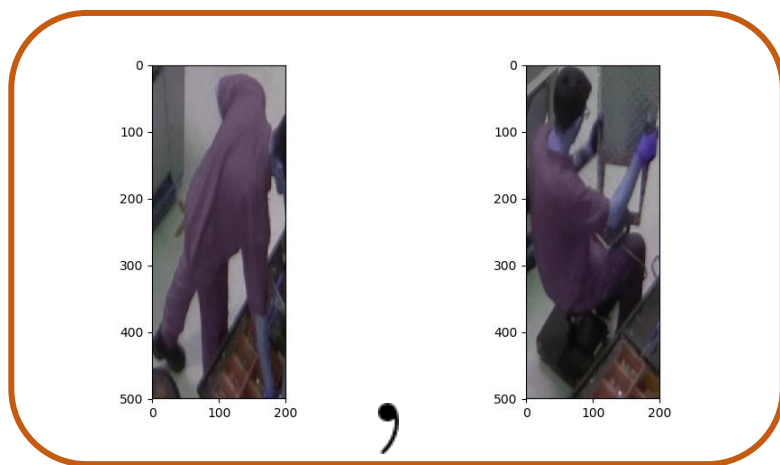


$\{0\}$

Path tracking: siamese network approach

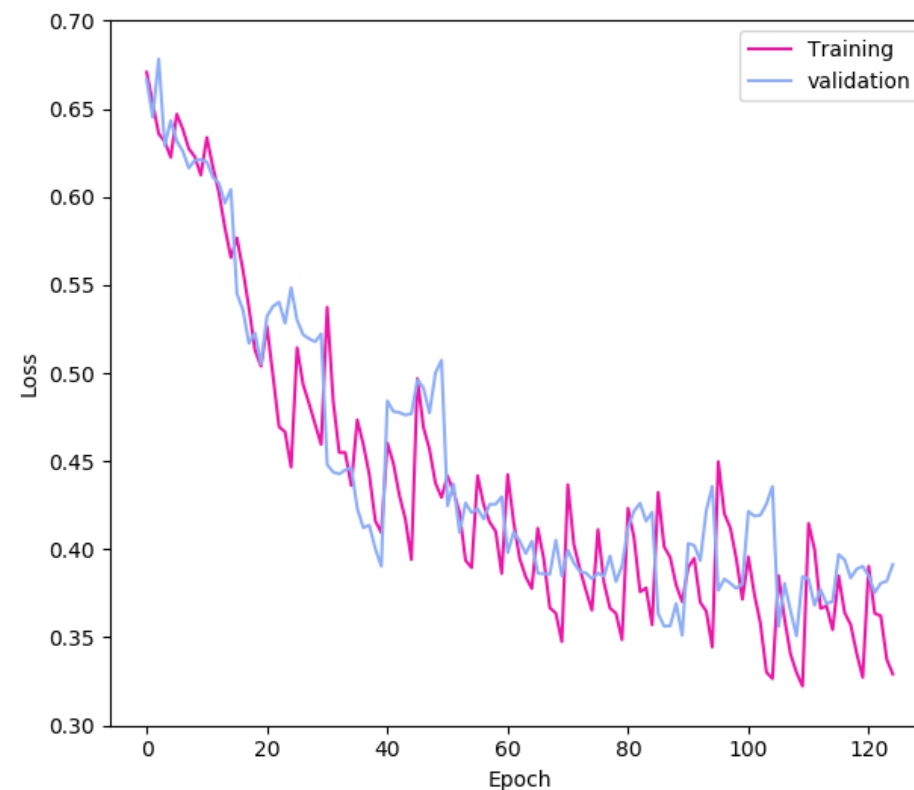
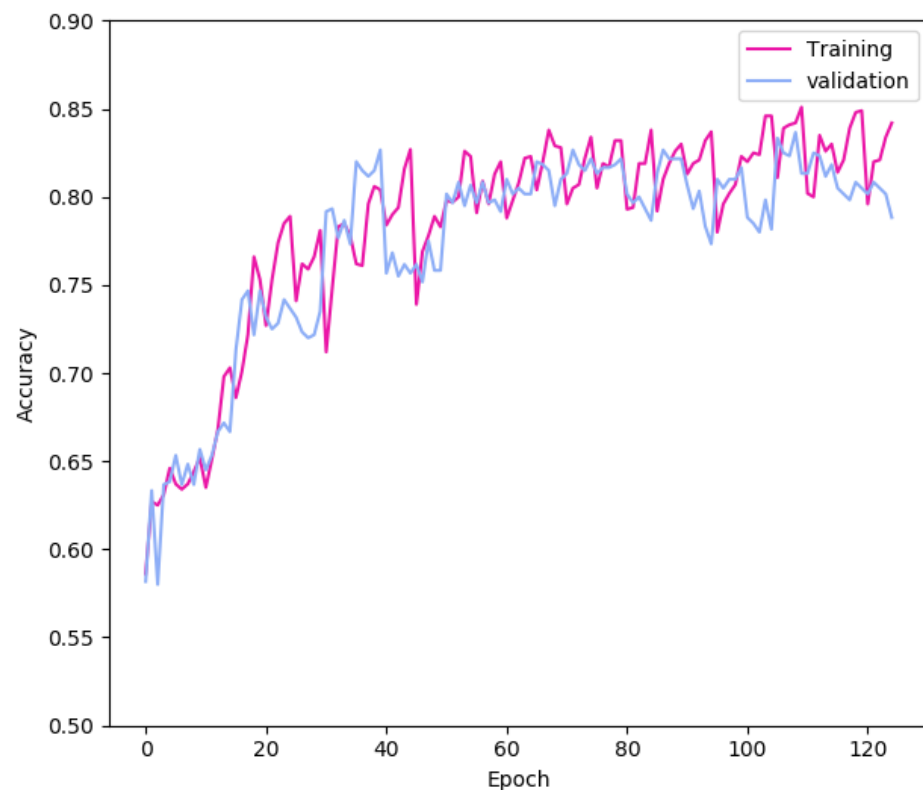


→ {0}



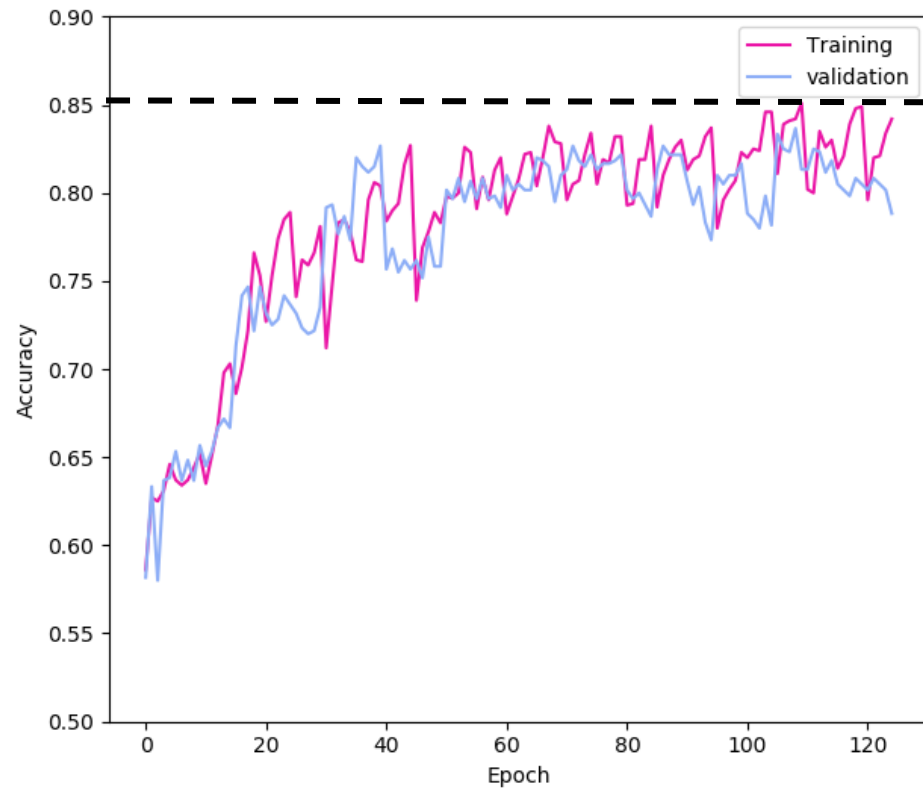
→ {1}

Training and validation loss for the siamese network approach



$$L_i = -y_i \log(\hat{y}_i) - (1 - y_i) \log(1 - \hat{y}_i)$$

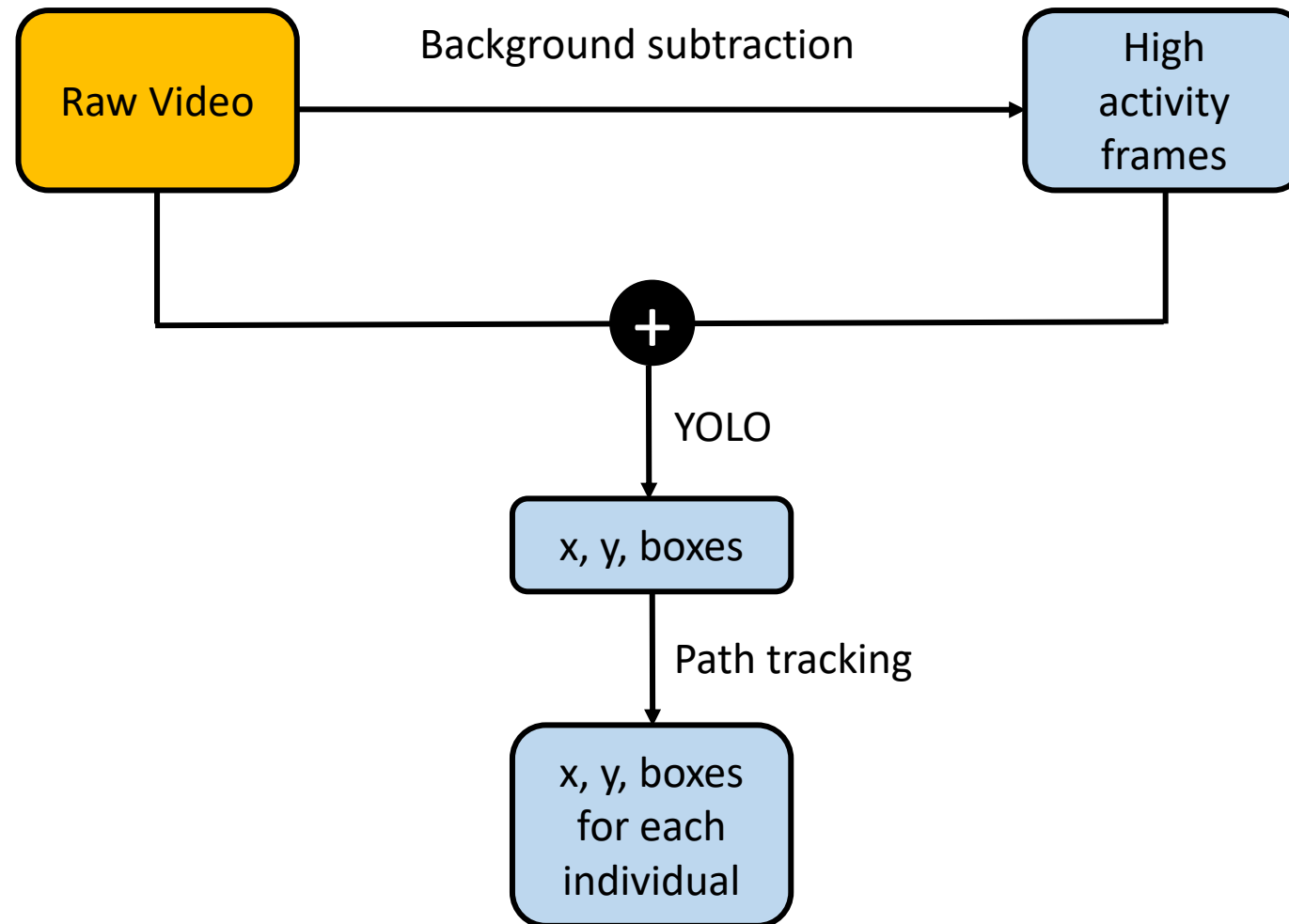
Training and validation loss for the siamese network approach



- The training and validation highly depends on how the data sets are selected.
- 13,000 pictures labeled.
- The accuracy could be improved by labeling more data and training on more epochs.

Conclusions

Pipeline



Summary and conclusions

- **Workers activities can be tracked** by using a combination of background subtraction and an object detection algorithm. However, **we require an additional tool to identify all the individuals** in the workshop.
- In comparison to different approaches, as CNN and unsupervised learning, **the siamese network approach works better.**
- Although the siamese network approach gives a good accuracy in both the training and the validation, **more data is need to** produce results with a higher fidelity and **solve the problem.**